

Hour 23, 24

Lecture 18

Lecture 19

(62)

§§ 4.5-4.6 The Lax-Wendroff Scheme

1. Consider

$$u_t + a(x,t) u_x = 0$$

$$u_t \sim \frac{U_j^{n+1} - U_j^n}{\Delta t}$$

$$\begin{aligned} u(x, t+\Delta t) &= u(x, t) + \Delta t u_t(x, t) + \frac{1}{2} (\Delta t)^2 u_{tt}(x, t) \\ &\quad + O(\Delta t^3) \end{aligned}$$

$$u_t = -a u_x$$

$$u_{tt} = -a_t u_x - a u_{xt} = -a_t u_x + a(a u_x)_x$$

$$\begin{aligned} u(x, t+\Delta t) &= u(x, t) - \Delta t a u_x + \frac{\Delta t^2}{2} [-a_t u_x + a(a u_x)_x] \\ &\quad + O(\Delta t^3) \end{aligned}$$

$$\begin{aligned} \frac{U_j^{n+1} - U_j^n}{\Delta t} &= -a_j^n \frac{U_{j+1}^n - U_{j-1}^n}{2 \Delta x} \\ &\quad + \frac{\Delta t}{2} \left\{ -a_t \Big|_j^n \frac{U_{j+1}^n - U_{j-1}^n}{2 \Delta x} \right. \\ &\quad \left. + \frac{a_j^n}{\Delta x} \left[ a_{j+1}^n \frac{U_{j+1}^n - U_j^n}{\Delta x} - a_{j-1}^n \frac{U_j^n - U_{j-1}^n}{\Delta x} \right] \right\} \\ a \text{ constant: } & O(\Delta t^2 + \Delta x^2) \end{aligned}$$

$$\frac{U_j^{n+1} - U_j^n}{\Delta t} = -a \frac{U_{j+1}^n - U_{j-1}^n}{2 \Delta x} + \frac{\Delta t a}{2 \Delta x} [\dots]$$

$$\sim u_t + \alpha u_x = \frac{\Delta t^3}{2} u_{xx}$$

$$u_t + \alpha u_x = \frac{\Delta t \alpha}{2} (u_x)_x \quad (\alpha_t = 0)$$

### Questions:

- truncation error  $O(\Delta t^2 + \alpha x^2)$

• convergence  $O(\Delta t^2 + \alpha x^2)$  if  $u$  is sufficiently smooth  
 (?) if  $u$  is non-smooth.

- stability (CFL)

$$\frac{\alpha \Delta t}{\Delta x} \leq 1$$

- phase and amplitude errors

$$\lambda(k) = 1 - 2\nu^2 \sin^2 \frac{1}{2} k \Delta x - i \nu \sin k \Delta x$$

$$|\lambda(k)| = \sqrt{1 - 4\nu^2(1-\nu^2) \sin^4 \frac{1}{2} k \Delta x}$$

damping but of order  $\xi^4 = (k \Delta x)^4$

$$\arg \lambda(k) = -\tan^{-1} \left[ \frac{\nu \sin k \Delta x}{1 - 2\nu^2 \sin^2 \frac{1}{2} k \Delta x} \right]$$

$$\sim -\nu \xi \left[ 1 - \frac{1}{6} (1-\nu^2) \xi^2 + \dots \right]$$

of order  $\xi^2 = (k \Delta x)^2$

- monotonicity (NOT!)

### Example

$$\left\{ \begin{array}{l} u_t + a(x,t) u_x = 0 \\ u(x,0) = \begin{cases} 1 & \text{if } 0.2 \leq x \leq 0.4 \\ 0 & \text{otherwise} \end{cases} \\ u(0,t) = 0 \end{array} \right.$$

$$a(x,t) = \frac{1+x^2}{1+2xt+2x^2+x^4}$$

$$\Delta t = \Delta x . \quad O((\Delta x)^{2/3})$$

Figure 4.7.

## 2. For conservation laws

$$u_t + (f(u))_x = 0$$

$$u(t+\Delta t) = u(t) + \Delta t u_t + \frac{\Delta t^2}{2!} u_{tt} + O(\Delta t^3)$$

$$u_t = - f_x$$

$$\begin{aligned} u_{tt} &= - f_{xt} = - (f_t)_x = - (f_u u_t)_x \\ &= + (f_u f_x)_x \end{aligned}$$

$$a(u) = f_u$$

$$u(t+\Delta t) = u(t) - \Delta t f_x + \frac{\Delta t^2}{2} (a f_x)_x$$

$$\frac{u_j^{n+1} - u_j^n}{\Delta t} = - \frac{f(u_{j+1}^n) - f(u_j^n)}{2 \Delta x}$$

$$+ \frac{\Delta t}{2 \Delta x} \left[ a_{j+1}^n \frac{f(u_{j+1}^n) - f(u_j^n)}{\Delta x} - a_{j+2}^n \right]$$

$$Q_{j+\frac{1}{2}}^n = Q(U_{j+\frac{1}{2}}^n) = \alpha \left( \frac{U_{j+1}^n + U_j^n}{2} \right)$$

$$U_t + f_x = \frac{\Delta t}{2} (\alpha f_x)_x$$

$$U_t + f_x = \frac{\Delta t}{2} (f_u^2 u_x)_x$$

↑ artificial viscosity

Example Burgers' Equation

$$U_t + U U_x = 0$$

$$U_t + \frac{1}{2} (U^2)_x = 0$$

$$U(x, 0) = e^{-10(4x-1)^2}$$

Figure 4.10

Variant of the Lax-Wendroff scheme

$$U_{j+\frac{1}{2}}^{n+\frac{1}{2}} = \frac{1}{2} [U_j^n + U_{j+1}^n] - \frac{1}{2} \left( \frac{\Delta t}{\Delta x} \right) [f(U_{j+1}^n) - f(U_j^n)]$$

$$U_j^{n+1} = U_j^n - \frac{\Delta t}{\Delta x} [f(U_{j+\frac{1}{2}}^{n+\frac{1}{2}}) - f(U_{j-\frac{1}{2}}^{n+\frac{1}{2}})]$$

Readings §§ 4.7, 4.8, 4.9

Box Scheme, Leap-frog scheme

Comparison of phase and amplitude errors.