

More general BCs and Linear problems

§2.13 and §2.15

Generalizations:

- 1°. More general BCs and linear problems
- 2°. Conservations and symmetries
- 3°. nonlinear equations
- 4°. Singular Problems
- 5°. mesh adaptation/movement

Part I BCs

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} & x \in (0,1), t > 0 \\ u(x,0) = u^0(x) \\ \frac{\partial u}{\partial x}(0,t) = \alpha(t)u(0,t) + g(t) & t > 0 \\ u(1,t) = 0 \end{cases}$$

Method 1 (Direct 1st Order)

$$x_j = j\Delta x, \Delta x = \frac{1}{J},$$

$$\frac{U_j^{n+1} - U_0^{n+1}}{\Delta x} = \alpha(t_{n+1}) U_0^{n+1} + g(t_{n+1})$$

based on (x_0, t_{n+1})

$$T_0^{n+1} = O(\Delta x)$$

Method 2 (Fictitious point, widely used)

$$x_j = j\Delta x, j = 0, 1, \dots, J$$

introduce $x_{-1} = -\Delta x, U_{-1}$ (fictitious point)

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based on (x_0, t_{n+1}) :

$$\frac{U_{+1}^{n+1} - U_{-1}^{n+1}}{2\Delta x} = \alpha(t_{n+1}) U_0^{n+1} + g(t_{n+1}) \quad (\text{BC})$$

$$\frac{U_D^n - U_0^n}{\Delta t} = \frac{1}{\Delta x^2} [U_1^n - 2U_0^n + U_{-1}^n]$$

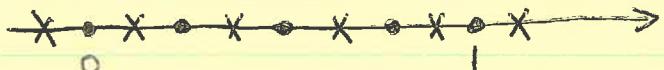
Method 3 (Staggered grid, widely used)

$$x_j = j \Delta x \quad j = 0, \dots, J-1$$

$$x_{j+\frac{1}{2}} = (j + \frac{1}{2}) \Delta x, \quad j = -1, 0, \dots, J$$

$$U_{j+\frac{1}{2}}^{n+1} \quad (j = -1, 0, 1, \dots, J)$$

interior points:



$$\left\{ \frac{U_{j+\frac{1}{2}}^{n+1} - U_{j-\frac{1}{2}}^n}{\Delta t} = \frac{1}{\Delta x^2} [U_{j+\frac{3}{2}}^n - 2U_{j+\frac{1}{2}}^n + U_{j-\frac{1}{2}}^n] \right.$$

based on $(x_{j+\frac{1}{2}}, t_n) \quad j = 0, 1, \dots, J-1$

$$\left. \frac{U_{j+\frac{1}{2}}^{n+1} - U_{j-\frac{1}{2}}^{n+1}}{\Delta x} = \alpha(t_{n+1}) \frac{U_{j+\frac{1}{2}}^{n+1} + U_{j-\frac{1}{2}}^{n+1}}{2} + g(t_{n+1}) \right.$$

$$\frac{U_{j+\frac{1}{2}}^{n+1} + U_{j-\frac{1}{2}}^{n+1}}{2} = 0$$

Part II

$$\frac{\partial u}{\partial t} = a(x, t) \frac{\partial^2 u}{\partial x^2} + b(x, t) \frac{\partial u}{\partial x} + c(x, t) u + d(x, t)$$

- the point based on
- explicit, Crank-Nicolson, implicit.
- stability, truncation errors, convergence.